

ELECTRICAL CHARACTERISTICS ($T_C = 25^\circ\text{C}$, $V_{in1} = V_{in2} = 12\text{ Vdc}$, $V_{EE} = 0$, $V_O = 5.0\text{ Vdc}$, $I_L = 10\text{ mAdc}$, unless otherwise noted.)

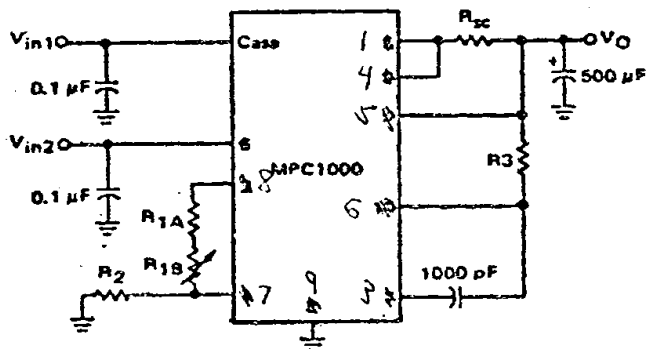
Characteristic	Figure No.	Note	Symbol	Min	Max	Unit
Input Voltage Range	2	1	V_{in2}	9.5	40	Vdc
Output Voltage Range	2	—	V_O	2.0	35	Vdc
Input-Output Voltage Differential ($I_L = 10\text{ mAdc}$)	2	2	$V_{in1} - V_O$	—	60	Vdc
			$V_{in2} - V_O$	—	38	
	2	2	$V_{in1} - V_O$	3.0	—	
			$V_{in2} - V_O$	5.0	—	
Reference Voltage	2	3	V_{ref}	6.8	7.5	Vdc
Standby Current Drain ($I_L = 0$, $V_{in1} = V_{in2} = 30\text{ Vdc}$, $V_O = 5.0\text{ Vdc}$)	2	8	I_{IB}	—	5.0	mAdc
Line Regulation ($V_{in1} = V_{in2} = 12\text{ Vdc to } 15\text{ Vdc}$) ($V_{in1} = V_{in2} = 12\text{ Vdc to } 40\text{ Vdc}$)	2	2,6	Reg_{in}	—	0.1	% V_O
	2	2,6	Reg_{in}	—	0.5	% V_O
	2	2,4,7	Reg_{load}	—	0.1	% V_O

TEMPERATURE PERFORMANCE ($I_L = 10\text{ mAdc}$, $V_O = 5.0\text{ Vdc}$, $V_{EE} = 0$, unless otherwise noted.)

Characteristic	Figure No.	Note	Symbol	Max	Unit
Line Regulation ($V_{in1} = V_{in2} = 12\text{ Vdc to } 15\text{ Vdc}$) $T_C = -55^\circ\text{C}$ $T_C = +125^\circ\text{C}$	2	2,6	Reg_{in}	0.5	% V_O
				0.5	% V_O
Load Regulation ($I_L = 100\text{ mAdc to } 4.0\text{ A}$, $V_{in1} = V_{in2} = 12\text{ Vdc}$) $T_C = -55^\circ\text{C}$ $T_C = +125^\circ\text{C}$	2	2,4,7	Reg_{load}	0.6	% V_O
				0.6	% V_O
Temperature Coefficient of Output Voltage ($V_{in1} = V_{in2} = 12\text{ Vdc}$, $I_L = 1.0\text{ A}$, $\Delta T_C = 180^\circ\text{C}$, $T_C = -55^\circ\text{C to } +125^\circ\text{C}$)	2	2,4,5	TC_{VO}	0.015	% V_O / $^\circ\text{C}$

TYPICAL CIRCUIT CONNECTIONS

FIGURE 2 — $V_O < V_{ref}$



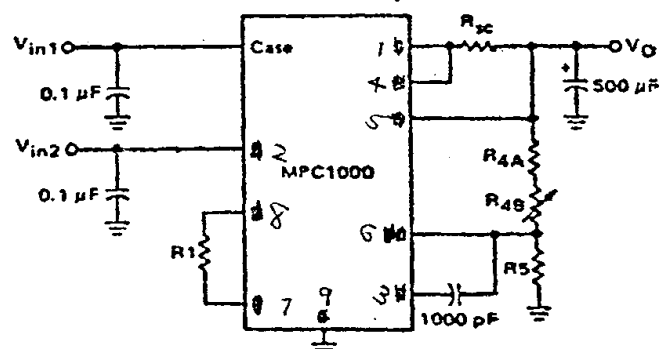
Parameter Values for Best Results

R_1	$\geq \frac{R_2 (V_{ref} - V_O)}{V_O}$
R_2	$10\text{ k} < R_1 + R_2 < 100\text{ k}$
R_3	$= \frac{R_1 R_2}{R_1 + R_2}$
R_{sc}	$\geq \frac{0.66}{I_{sc}} @ T_J = 25^\circ\text{C}$

To Allow For Variations In V_{ref}

- (1) $R_{1A} < \frac{R_{2min} (V_{ref(min)} - V_O)}{V_O}$
- (2) $(R_{1A} + R_{1B}) \geq \frac{R_{2max} (V_{ref(max)} - V_O)}{V_O}$

FIGURE 3 — $V_O > V_{ref}$



Parameter Values for Best Results

R_1	$= \frac{R_4 R_5}{R_4 + R_5}$
R_4	$\geq \frac{R_5 (V_O - V_{ref})}{V_{ref}}$
R_5	$10\text{ k} < R_4 + R_5 < 100\text{ k}$
R_{sc}	$\geq \frac{0.66}{I_{sc}} @ T_J = 25^\circ\text{C}$

To Allow For Variations In V_{ref}

- (1) $R_{4A} < \frac{R_{5min} (V_O - V_{ref(min)})}{V_{ref(min)}}$
- (2) $(R_{4A} + R_{4B}) \geq \frac{R_{5max} (V_O - V_{ref(max)})}{V_{ref(max)}}$

In most applications V_{in1} and V_{in2} can be connected together to eliminate one of the two capacitors shown in the above connection diagram. In either situation all capacitors should be as close as possible to the device to minimize lead inductance.



MOTOROLA Semiconductor Products Inc.

1. "Minimum Input Voltage" is the minimum "total instantaneous input voltage" required to properly bias the internal zener reference diode.
2. Set $R_{sc} = 0$ (short circuit)
3. V_{ref} voltage is measured from Pin 2 to Pin 3.
4. Pulse test conditions: Load current must be switched from minimum to maximum value at a repetition rate of 10 pps or less with a duty cycle of 1% or less in order to minimize heating effects.
5. The temperature coefficient of output voltage is defined as:

$$TCVO = \frac{\pm(V_{O \max} - V_{O \min})}{(\Delta T_C)(V_O @ T_C = 25^\circ C)} (100)$$

6. The input line regulation is defined as:

$$Reg_{in} = \frac{\pm(V_O @ V_{in \text{ high}} - V_O @ V_{in \text{ low}})}{V_O @ V_{in \text{ low}}} \times 100$$

7. Load regulation is defined as:

$$Reg_{load} = \frac{\pm(V_O @ I_{L \text{ low}} - V_O @ I_{L \text{ high}})}{(V_O @ I_{L \text{ low}})} (100)$$

8. Standby current drain is defined as that value of current measured at Pins 6 and Case when R_L is open circuited.

FIGURE 3 — ACTIVE-REGION SAFE OPERATING AREA

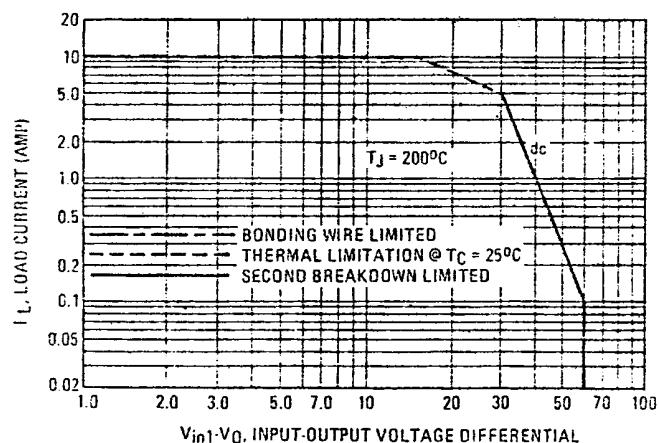
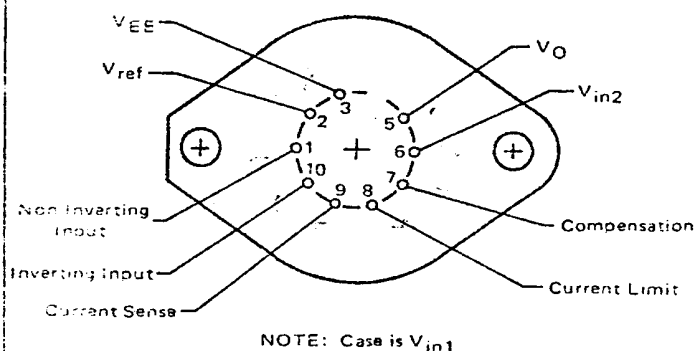


FIGURE 4 — PIN CONNECTION — BOTTOM VIEW



There are two limitations on the power handling ability of a power semiconductor: average junction temperature and second breakdown. Safe operating area curves indicate I_L , $(V_{in1} - V_O)$ limits of the circuit that must be observed for reliable operation;

FIGURE 5 — CURRENT LIMITING CHARACTERISTICS

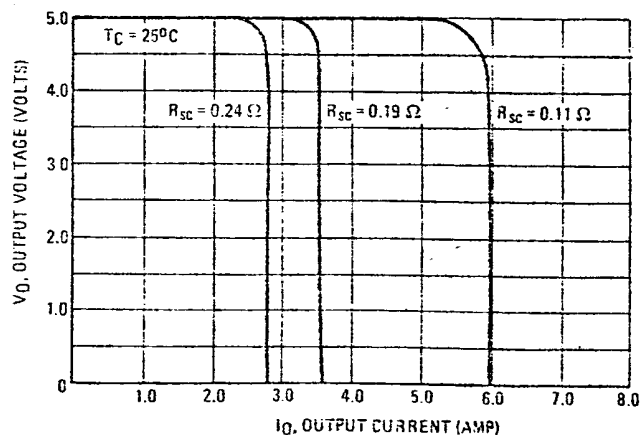


FIGURE 6 – LINE REGULATION AS A FUNCTION OF INPUT-OUTPUT VOLTAGE DIFFERENTIAL

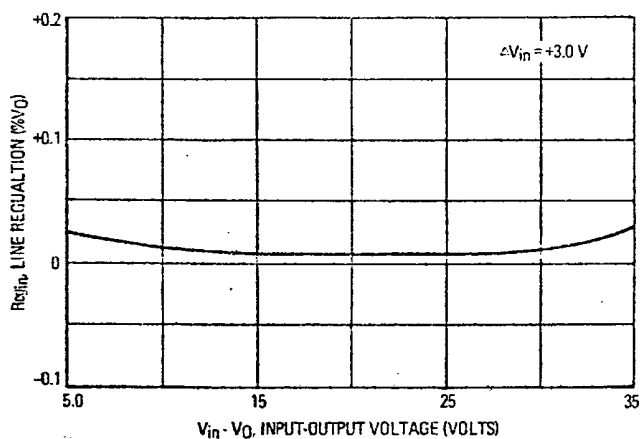


FIGURE 7 – STANDBY CURRENT DRAIN AS A FUNCTION OF INPUT VOLTAGE

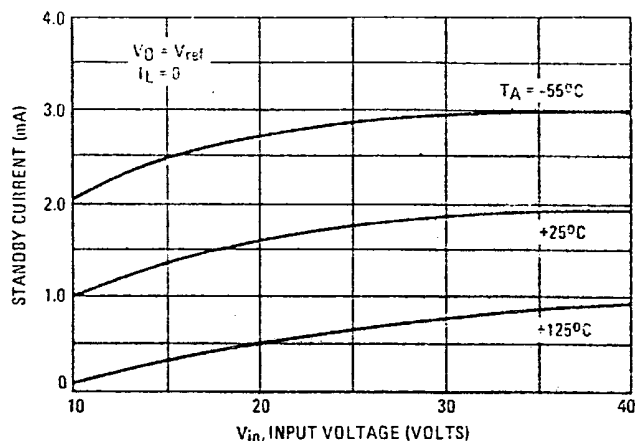


FIGURE 8 – LOAD TRANSIENT RESPONSE

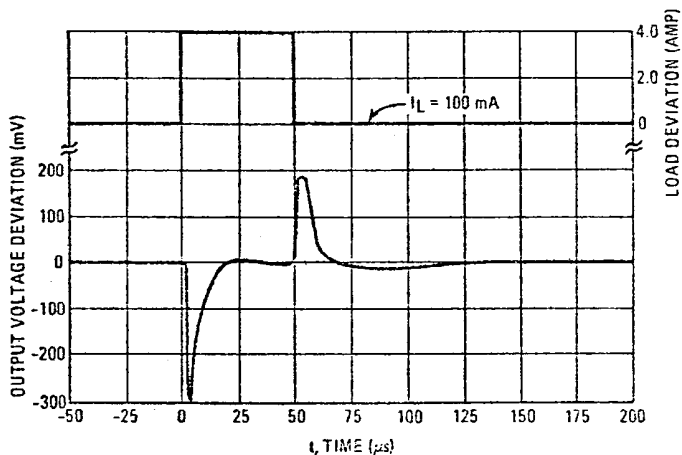


FIGURE 9 – LOAD REGULATION CHARACTERISTICS WITHOUT CURRENT LIMITING

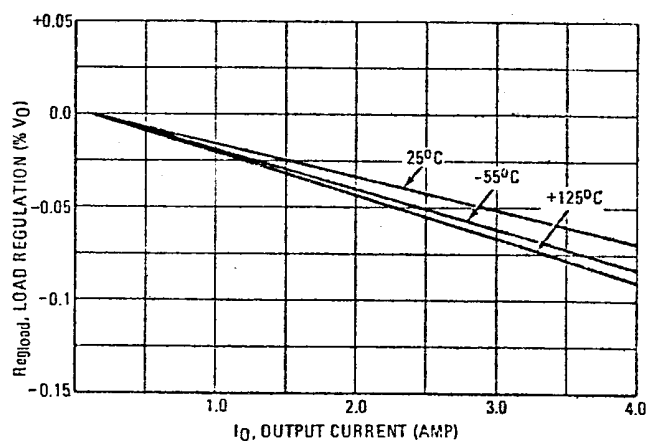
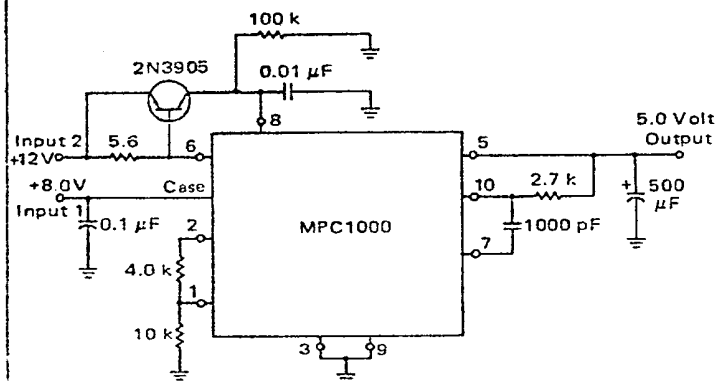
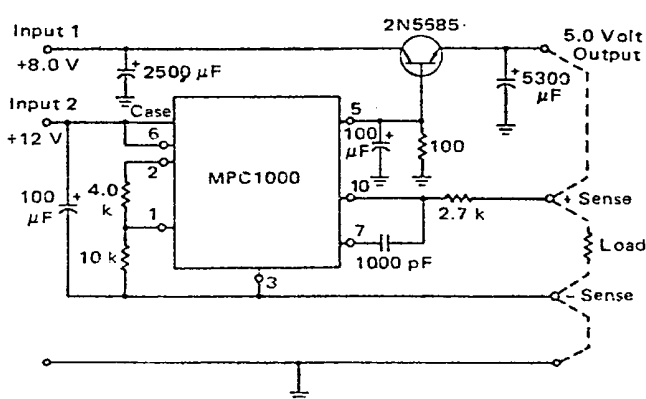


FIGURE 10 – 5 VOLT, 10 AMPERE HIGH EFFICIENCY REGULATOR



Regulator is protected by current limiting if input 1 is removed.

FIGURE 11 – 5 VOLT, 50 AMPERE POWER REGULATOR WITH REMOTE SENSE



MOTOROLA Semiconductor Products Inc.

BOX 20912 • PHOENIX, ARIZONA 85036 • A SUBSIDIARY OF MOTOROLA INC.